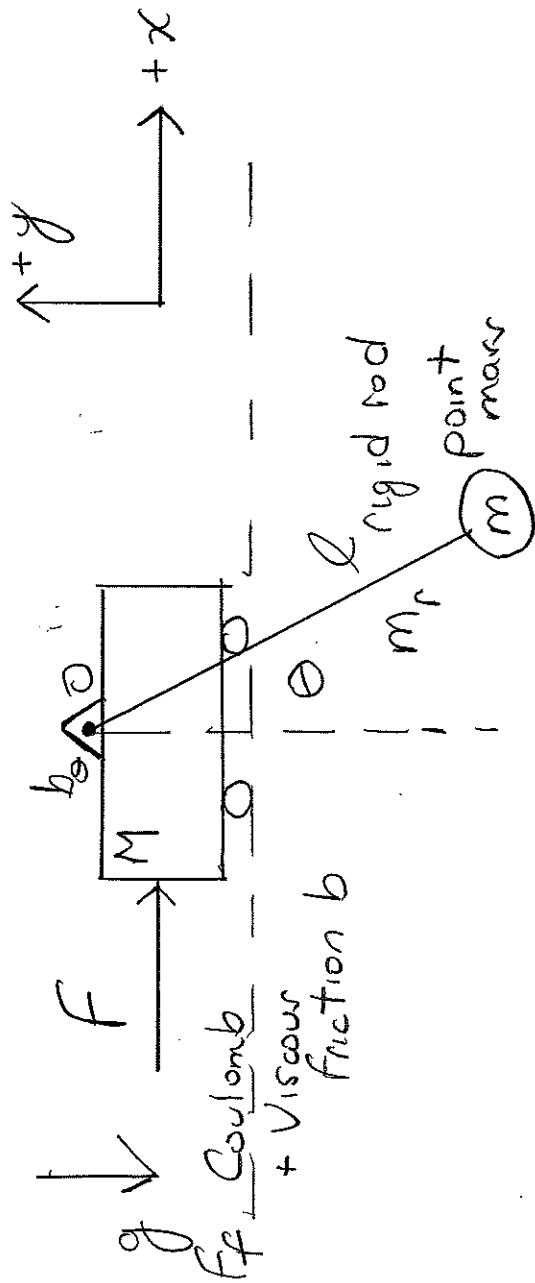
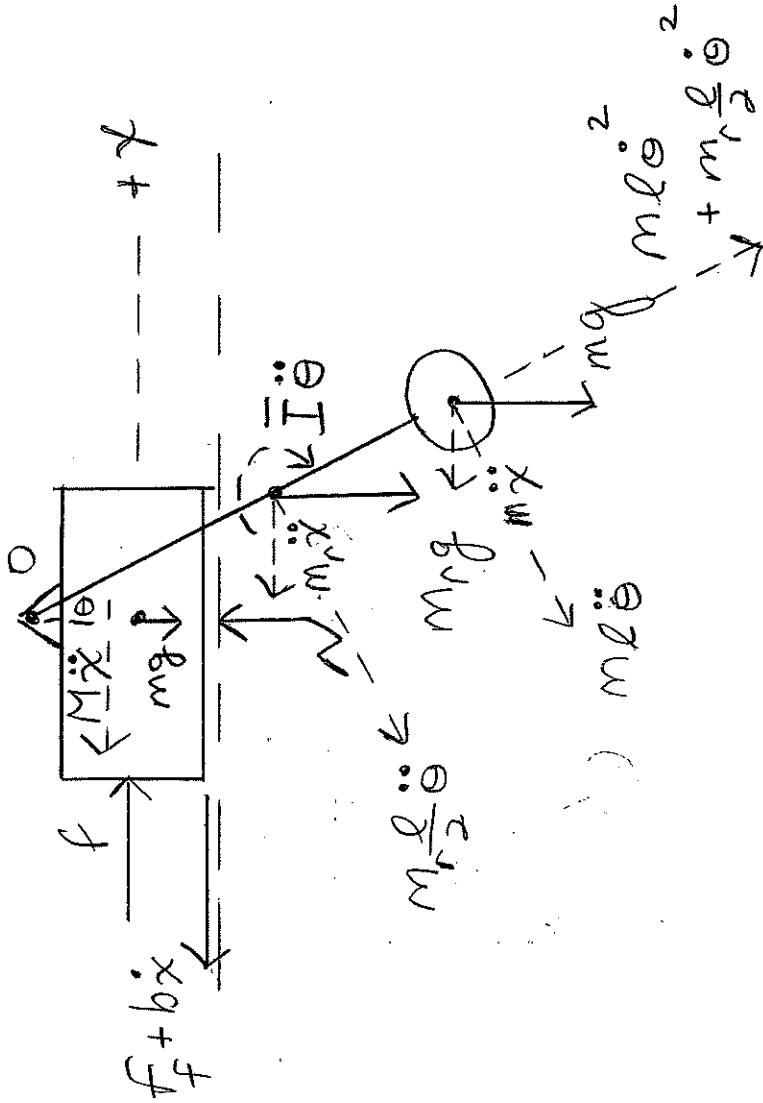


# Overhead-Crane Pneumatic-Gantry

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2 Dof:  $x, \theta$



$$\sum f_x = 0 \quad (\text{cart} + \text{pendulum FBD})$$

$$-f_f - b\dot{x} - M\ddot{x} - m_r\ddot{x} - m\ddot{x} - m_r l \ddot{\theta} \cos\theta - m l \ddot{\theta} \cos\theta + m l \dot{\theta}^2 \sin\theta + m_r \frac{l}{2} \dot{\theta}^2 \sin\theta + f = 0$$

$$(M + m_r + m)\ddot{x} + (m_r \frac{l}{2} + m l) \cos\theta \ddot{\theta} - (m l + m_r \frac{l}{2}) \sin\theta \dot{\theta}^2 + b\dot{x} + f_f = f$$

$$\sum M_o = 0 \quad \checkmark \quad (\text{pendulum FBD})$$

$$-I\ddot{\theta} - m\ddot{x} l \cos\theta - m_r \ddot{x} \frac{l}{2} \cos\theta + m g l \sin\theta - m r g \frac{l}{2} \sin\theta - m l \ddot{\theta} - m_r \left(\frac{l}{2}\right)^2 \ddot{\theta} - b_{\theta} \dot{\theta} = 0$$

$$(m l^2 + m_r \frac{l^2}{4}) \ddot{\theta} + (m l + m_r \frac{l}{2}) g \sin\theta + I \ddot{\theta} + (m l + m_r \frac{l}{2}) \ddot{x} \cos\theta + b_{\theta} \dot{\theta} = 0$$

$$I = \frac{1}{12} m_r l^2$$

## Summary

$$(M + m_r + m) \ddot{x} + b \dot{x} + f_x + \left(\frac{m_r l}{2} + m l\right) \cos \theta \ddot{\theta}$$

$$- (m l + \frac{m_r l}{2}) \sin \theta \dot{\theta}^2 = F \quad [1]$$

$$(m l^2 + m_r \frac{l^2}{4}) \ddot{\theta} + \left(\frac{1}{12} m_r l^2\right) \ddot{\theta} + (m l + \frac{m_r l}{2}) g \sin \theta$$

$$+ (m l + \frac{m_r l}{2}) \dot{x} \cos \theta + b_\theta \dot{\theta} = 0 \quad [2]$$

Assume :  $\sin \theta \approx \theta$     $\cos \theta \approx 1$     $\dot{\theta}^2 \approx 0$

$$(M + m_r + m) \ddot{x} + b \dot{x} + f_x + \left(\frac{m_r}{2} + m\right) l \ddot{\theta} = F \quad [3]$$

$$\left(m l^2 + \frac{m_r l^2}{4} + \frac{1}{12} m_r l^2\right) \ddot{\theta} + (m + \frac{m_r}{2}) l g \theta + (m + \frac{m_r}{2}) l \dot{x} = 0$$

$$(m + \frac{m_r}{3}) l^2 \ddot{\theta} + (m + \frac{m_r}{2}) l g \theta + (m + \frac{m_r}{2}) l \dot{x} + b_\theta \dot{\theta} = 0$$

$$(m + \frac{m_r}{3}) l \ddot{\theta} + (m + \frac{m_r}{2}) g \theta + (m + \frac{m_r}{2}) \dot{x} + \frac{b_\theta}{l} \dot{\theta} = 0 \quad [4]$$

## Linear Equations

( $f_f = \text{Coulomb friction - nonlinear}$ )

$$(M + m_r + m) \ddot{x} + b \dot{x} + \left(\frac{m_r}{2} + m\right) l \ddot{\theta} = F$$

$$\left(m + \frac{m_r}{3}\right) l \ddot{\theta} + (m + m_r) g \theta + (m + \frac{m_r}{2}) \ddot{x} + \frac{b \theta}{l} \dot{\theta} = 0$$

Define  $\left(m + \frac{m_r}{2}\right) \equiv c_2$

$$\left(m + \frac{m_r}{3}\right) \equiv c_3$$

$$(M + m_r + m) \equiv D_1$$

$$\frac{b \theta}{l} \equiv D$$

$$c_1 \ddot{x} + b \dot{x} + c_2 l \ddot{\theta} = F$$

[5]

$$c_3 l \ddot{\theta} + c_2 g \theta + c_2 \ddot{x} + D \dot{\theta} = 0$$

[6]

$$c_1 \ddot{x} + b \dot{x} + c_2 l \ddot{\theta} = f \rightarrow \ddot{\theta} = \frac{1}{c_2 l} [f - c_1 \ddot{x} - b \dot{x}] \quad 4a$$

$$c_3 l \ddot{\theta} + c_2 g \theta + c_2 \ddot{x} + d \dot{\theta} = 0 \rightarrow \ddot{x} = \frac{1}{c_2} [-c_3 l \ddot{\theta} - c_2 g \theta - d \dot{\theta}]$$

$$\left\{ \begin{aligned} c_1 \left[ \frac{1}{c_2} (-c_3 l \ddot{\theta} - c_2 g \theta - d \dot{\theta}) \right] + b \dot{x} + c_2 l \ddot{\theta} &= f \\ -\frac{c_1}{c_2} c_3 l \ddot{\theta} - c_1 g \theta - \frac{c_1 d}{c_2} \dot{\theta} + b \dot{x} + c_2 l \ddot{\theta} &= f \\ \left[ c_2 l - \frac{c_1 c_3}{c_2} \right] l \ddot{\theta} - \frac{c_1 d}{c_2} \dot{\theta} - c_1 g \theta + b \dot{x} &= f \quad [5a] \end{aligned} \right.$$

$$c_3 l \left[ \frac{1}{c_2} l (f - c_1 \ddot{x} - b \dot{x}) \right] + c_2 g \theta + c_2 \ddot{x} + d \dot{\theta} = 0$$

$$\frac{c_3}{c_2} f - \frac{c_1 c_3}{c_2} \ddot{x} - \frac{c_3 b}{c_2} \dot{x} + c_2 g \theta + c_2 \ddot{x} + d \dot{\theta} = 0$$

$$\left[ c_2 - \frac{c_1 c_3}{c_2} \right] \ddot{x} - \frac{c_3 b}{c_2} \dot{x} + c_2 g \theta + d \dot{\theta} = -\frac{c_3}{c_2} f \quad [6a]$$

$$\begin{bmatrix} (c_1 s^2 + bs) & c_2 r s^2 \\ c_2 s^2 & (c_3 r s^2 + ds + c_2 g) \end{bmatrix} \begin{bmatrix} X \\ \Theta \end{bmatrix} = \begin{bmatrix} F \\ 0 \end{bmatrix}$$

$$\begin{aligned} \text{Den} &= (c_1 s^2 + bs)(c_3 r s^2 + ds + c_2 g) - (c_2 r s^2)(c_2 s^2) \\ &= c_1 c_3 r s^4 + c_1 d s^3 + c_3 b r s^2 + c_2 g s^2 + c_2 r s^2 \\ &= (c_1 c_3 r) s^4 + (c_1 d + c_3 b r) s^3 + (c_2 g + c_2 r) s^2 + (c_2 g) s \end{aligned}$$

$$\text{Num}_X = (F)(c_3 r s^2 + ds + c_2 g)$$

$$\text{Num}_\Theta = (F)(c_2 s^2)$$

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$$G_1(s) = \frac{\Theta}{X}(s) = \frac{B_2 s + s p + z_2 s^2}{C_3 s^2}$$

$$G_2(s) = \frac{X}{F}(s) = \frac{C_3 s^2 + p s + C_2 s}{(C_1 C_3 e)^4 s^4 + s^3 (p q + b d) + (C_1 C_2 + b d) s^2 + (C_1 C_2 + b d) s}$$

$$G_3(s) = \frac{\Theta}{F}(s) = \frac{C_2 s^2}{(C_1 C_3 e)^4 s^4 + s^3 (p q + b d) + (C_1 C_2 + b d) s^2 + (C_1 C_2 + b d) s}$$